

TURING MACHINES

TMs model the computing capability of a general purpose computer, which informally can be described as:

Effective procedure Finitely describable Well defined, discrete, "mechanical" steps Always terminates Computable function A function computable by an effective procedure

TMs formalize the above notion.

Church-Turing Thesis: There is an effective procedure for solving a problem if and only if there is a TM that halts for all inputs and solves the problem.

There are many other computing models, but all are equivalent to or subsumed by TMs. *There is no more powerful machine* (Technically cannot be proved).

DFAs and PDAs do not model all effective procedures or computable functions, but only a subset.

Deterministic Turing Machine (DTM)















So the successor's output on 111101 was 000011 which is the reverse binary representation of 48. Similarly, the successor of 127 should be 128:





















- Two-way, infinite tape, broken into cells, each containing one symbol.
- Two-way, read/write tape head.
- An input string is placed on the tape, padded to the left and right infinitely with blanks, read/write head is
 positioned at the left end of input string.
- Finite control, i.e., a program, containing the position of the read head, current symbol being scanned, and the current state.
- In one move, depending on the current state and the current symbol being scanned, the TM
 - 1) changes state,
 - 2) prints a symbol over the cell being scanned, and
 - 3) moves its' tape head one cell left or right.
- Many modifications possible, but Church-Turing declares equivalence of all.

Formal Definition of a DTM

• A DTM is a seven-tuple:

 $M = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$

- Q A <u>finite</u> set of states
- Σ A <u>finite</u> input alphabet, which is a subset of Γ {B}
- Γ A <u>finite</u> tape alphabet, which is a strict <u>superset</u> of Σ
- B A distinguished blank symbol, which is in Γ
- q_0 The initial/starting state, q_0 is in Q
- F A set of final/accepting states, which is a subset of Q
- δ A next-move function, which is a *mapping* (i.e., may be undefined) from

 $Q \ge \Gamma \rightarrow Q \ge \Gamma \ge \{L,R\}$

Intuitively, $\delta(q,s)$ specifies the next state, symbol to be written, and the direction of tape head movement by M after reading symbol s while in state q.



The Halting Problem

- Definition: A <u>decision problem</u> is a problem having a yes/no answer (that one presumably wants to solve with a computer). Typically, there is a list of parameters on which the problem is based.
 - Given a list of numbers, is that list sorted?
 - Given a number x, is x even?
 - Given a C program, does that C program contain any syntax errors?
 - Given a TM (or C program), does that TM contain an infinite loop?

From a practical perspective, many decision problems do not seem all that interesting. However, from a theoretical perspective they are for the following two reasons:

- Decision problems are more convenient/easier to work with when proving complexity results.
- Non-decision *counter-parts* can always be created & are typically at least as difficult to solve.